

## RT5 - Zephyr RTOS Programming

### Comprehensive Zephyr OS training from Theory to Practice

#### Objectives

- Learn how to develop, configure, debug and trace Zephyr applications
- Devicetree and Kconfig usage and development
- Using west and writing west manifest
- Zephyr real time multitasking overview
- Understand the Zephyr kernel Services and ecosystem
- Learn communication and synchronization mechanisms
- Understand Zephyr memory management and data structures
- Understand User mode and kernel mode
- Writing a device tree, and driver
- Using common subsystems

#### Course Environment

- Theoretical course
  - PDF course material (in English) supplemented by a printed version.
  - The trainer answers trainees' questions during the training and provide technical and pedagogical assistance.
- Practical activities
  - Practical activities represent from 40% to 50% of course duration.
  - Code examples, exercises and solutions
  - One PC (Linux ou Windows) for the practical activities with, if appropriate, a target board.
    - ▶ One PC for two trainees when there are more than 6 trainees.
  - For onsite trainings:
    - ▶ An installation and test manual is provided to allow preinstallation of the needed software.
    - ▶ The trainer come with target boards if needed during the practical activities (and bring them back at the end of the course).
- Downloadable preconfigured virtual machine for post-course practical activities
- At the start of each session the trainer will interact with the trainees to ensure the course fits their expectations and correct if needed

#### Prerequisites

- Good C programming skills (see our [L2 - C language for Embedded MCU](#) course)

#### Duration

- Total: 5 days
- From 40% to 50% of training time is devoted to practical activities
- Some Labs may be completed between sessions and are checked by the trainer on the next session

#### Target Audience

- Any embedded systems engineer or technician with the above prerequisites.

## Evaluation modalities

- The prerequisites indicated above are assessed before the training by the technical supervision of the trainee in his company, or by the trainee himself in the exceptional case of an individual trainee.
- Trainee progress is assessed in two different ways, depending on the course:
  - For courses lending themselves to practical exercises, the results of the exercises are checked by the trainer while, if necessary, helping trainees to carry them out by providing additional details.
  - Quizzes are offered at the end of sections that do not include practical exercises to verify that the trainees have assimilated the points presented
- At the end of the training, each trainee receives a certificate attesting that they have successfully completed the course.
  - In the event of a problem, discovered during the course, due to a lack of prerequisites by the trainee a different or additional training is offered to them, generally to reinforce their prerequisites, in agreement with their company manager if applicable.

## Plan

### First Day

## Introduction to Zephyr

- Zephyr Project
- Zephyr Ecosystem
- Why use Zephyr
- Install and use Zephyr
- Build and Configuration Systems
  - West
  - CMake
  - Zephyr SDK
- Application components and structure
- West manifest

## Configure Zephyr

- Overview
- Kconfig
  - Default configuration
  - Interactive configuration tools
  - Config fragments
- Devicetree
  - Syntax
  - Standard properties
  - Initial devicetree source
  - Access devicetree from source code
  - Best practices

*Exercise: Write a device tree overlay*

## Zephyr Without Threads

- Operation without Threads
- GPIO subsystem
- Utilities
  - Container\_of
  - For\_each
- Data Structures
  - Single-linked List
  - Double-linked List
  - Ring Buffers

*Exercise: Hello World from Zephyr, configure and blink LEDs using Zephyr*

*Exercise: Manage Zephyr linked list and understand container\_of macro*

## Second Day

### **Thread Management**

- Thread Fundamentals
  - Thread Control Block
  - Creating Threads
  - Threads Priorities
  - Changing Thread Priority
  - Thread States
- Main and Idle Threads
- Delays
- Suspending Threads
- Kernel Structures
  - Simple linked-list ready queue
  - Red/black tree ready queue
  - Traditional multi-queue ready queue
- Thread Custom Data

*Exercise: Create and manage threads*

*Exercise: Create periodic threads*

### **Tracing and logging**

- Runtime Statistics
- Scheduling Traces
  - User-Defined Tracing
  - Percepio Tracealyzer

*Exercise: Create config fragment for visual trace diagnostics using Tracealyzer*

### **Memory Management in Zephyr**

- Memory Managers
- Dynamic memory managers
  - K\_heap
  - System heap
  - Memory Slabs
  - Memory Blocks
- Heap Listeners
- Thread Resource Pools
- RAM/ROM reports
- Stack information
  - Stack Overflow detection
  - Stack analysis

*Exercise: Understand dynamic memory allocation in Zephyr*

*Exercise: Display threads information and detect stack overflow*

## Third Day

### **User Mode**

- Overview
- Memory Domains
  - Partitions
  - Logical apps
- Syscalls
  - Kernel objects
  - Permissions

## Resource Management and Synchronization

- Mutual Exclusion
- Mutexes
- Gatekeeper threads
- Critical Sections
- Atomic
- SpinLocks
- Semaphores
- Events
- Polling

*Exercise: The producer-consumer problem, synchronize and avoid concurrent access problems*

*Exercise: Understanding event bit group by synchronizing several threads*

## Data Passing

- Message Queues
- Queues
  - FIFOs
  - LIFOs
- Mailboxes
- Pipes
- Stacks
- Zephyr Bus (Zbus)
  - Zbus overview
  - Elements
  - Usage

*Exercise: Create a print gatekeeper thread using message queue*

*Exercise: Synchronous communication using mailboxes*

## Fourth Day

## Interrupt Management

- Threads and Interrupts
- Interrupts in zephyr
- Interrupts on ARM Cortex-M
- Handler thread
- Queue within an ISR
- Workqueue Threads

*Exercise: Understand how to wait on multiple events and interrupt safe APIs*

*Exercise: Understand how to pass data using Queues from an interrupt to a thread*

*Exercise: Create and submit work items from interrupts to custom WorkQueue*

## Software Timers

- Timers
  - Defining a Timer
  - Using a Timer Expiry Function
- Timer types
  - One-shot timers
  - Auto-reload timers
- Timer Commands

*Exercise: Understand the use of one-shot and auto-reload timers*

## Modules

- Why to use modules?

- Module structure
- Out-of-tree module
- YAML files
- Module CMakeLists.txt

*Exercise: Create a simple hello world module*

## Kconfig

- Advantages
- Kconfig Options in Zephyr RTOS
- Configuration System
- Writing custom Kconfig Options
- Kconfig extension
- Using Kconfigs

*Exercise: Create a module that uses custom Kconfig options*

## Fifth Day

### Zephyr device driver model

- Introduction to Device Drivers
- Overview of the Zephyr device driver model
- Standard Drivers
- The struct device
- Subsystems
- API Extensions
- Initialization Levels
- Dependencies between device drivers
- Define devices programmatically

*Exercise: Create a driver that respects the Zephyr Device Driver Model and define devices*

### Device Trees in Zephyr

- Overview of Device Tree (DT) and its role in Zephyr
- Device Tree VS Kconfig
- Device Tree node structure
- Device Tree bindings
- Overlay and yaml files
- APIs to access device tree properties
- Write device drivers using device tree APIs
- Device Tree in Zephyr VS Linux
- Adding In-Tree Code to Zephyr Source Code
- Common properties
  - compatible
  - reg
  - interrupts

*Exercise: Create a driver that uses custom device tree and Kconfig*

*Exercise: Writing in-tree drivers*

### Power Management

- Overview
- System Power Management
- Device Power Management
  - System-Managed
  - Runtime
- Power domains

*Exercise: Write a driver compatible with power management subsystem*

Renseignements pratiques

**Inquiry : 5 days**